

**CURVILINEAR AND SURFACE INTEGRALS
 FUNCTIONS OF MANY VARIABLES**

<p>In E^3 with ONB :</p>	<p>Scalar field $f(\vec{r}) = f(x, y, z)$</p>	<p>Vector field $\vec{F}(\vec{r}) = \begin{cases} P(x, y, z) \\ Q(x, y, z) \\ R(x, y, z) \end{cases}$</p>
<p>Line I $\vec{r} = \vec{r}(t) \ t \in [\alpha, \beta]$</p> <p>or in coordinates $\begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases}$</p> <p>Functions $x(t), y(t), z(t)$ are continuously differentiable on $t \in [\alpha, \beta]$</p>	<p><i>Curvilinear integral of the first kind</i></p> $\int_I f(x, y, z) dl =$ $= \int_{\alpha}^{\beta} f(x(t), y(t), z(t)) \sqrt{x_i'^2 + y_i'^2 + z_i'^2} dt$	<p><i>Curvilinear integral of the second kind</i></p> $\int_I P dx + Q dy + R dz =$ $= \int_{\alpha}^{\beta} (P(x(t), y(t), z(t))x_i' + Q(x(t), y(t), z(t))y_i' + R(x(t), y(t), z(t))z_i') dt$
<p>Surface S</p> <p>$\vec{r} = \vec{r}(u, v) \ (u, v) \in \Omega \subseteq E^2$</p> <p>or in coordinates $\begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases}$</p> <p>Functions $x(u, v), y(u, v), z(u, v)$ are continuously differentiable on $(u, v) \in \Omega \subseteq E^2$</p>	<p><i>Surface integral of the first kind</i></p> $\iint_S f(x, y, z) ds =$ $= \iint_{\Omega} f(x(u, v), y(u, v), z(u, v)) \sqrt{EG - F^2} du dv,$ <p>where</p> $E = \left(\frac{\partial x}{\partial u}\right)^2 + \left(\frac{\partial y}{\partial u}\right)^2 + \left(\frac{\partial z}{\partial u}\right)^2$ $G = \left(\frac{\partial x}{\partial v}\right)^2 + \left(\frac{\partial y}{\partial v}\right)^2 + \left(\frac{\partial z}{\partial v}\right)^2$ $F = \frac{\partial x}{\partial u} \frac{\partial x}{\partial v} + \frac{\partial y}{\partial u} \frac{\partial y}{\partial v} + \frac{\partial z}{\partial u} \frac{\partial z}{\partial v}$	<p><i>Surface integral of the second kind</i></p> $\iint_S P dy dz + Q dz dx + R dx dy =$ $= \iint_{\Omega} \begin{vmatrix} P(x(u, v), y(u, v), z(u, v)) & Q(\dots\dots\dots) & R(\dots\dots\dots) \\ x_u' & y_u' & z_u' \\ x_v' & y_v' & z_v' \end{vmatrix} du dv$

Table 5.1

Properties of curvilinear and surface integrals

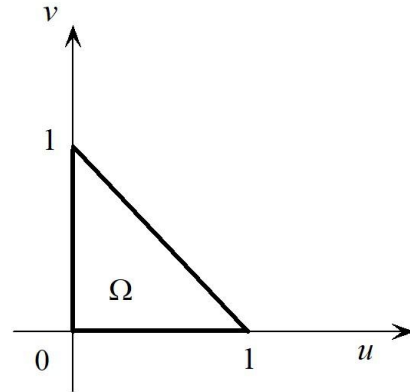
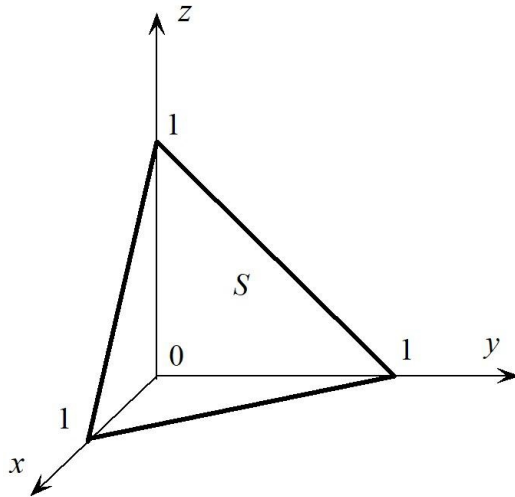
A curvilinear integral of the first kind does not change sign when changing the direction of traversal, but of the second kind it changes sign.

A surface integral of the first kind does not change sign when the surface orientation changes, but a surface integral of the second kind does not change sign.

Properties of the second kind curvilinear integral of the total differential:

- depends only on the starting and ending points of the line and does not depend on the shape of the line,
- the value along a closed contour (within which there are no special points) is equal to zero.

Example 01 .Calculate $I = \iint_S xyz \, ds$, Where $S: \begin{cases} x + y + z = 1, \\ x \geq 0, \\ y \geq 0, \\ z \geq 0 \end{cases}$.



Solution: 1) Parameterize the surface $S: \begin{cases} x(u, v) = u, \\ y(u, v) = v, \\ z(u, v) = 1 - u - v, \end{cases}$
 Where $(u, v) \in \Omega$.

2) In our case $f(x(u, v), y(u, v), z(u, v)) = uv - u^2v - uv^2$.

3) Find $E = 2, G = 2, F = 1 \quad \sqrt{EG - F^2} = \sqrt{3}$.

4) Formulate and calculate the integral $I = \iint_{\Omega} (uv - u^2v - uv^2)\sqrt{3} \, dudv = \frac{\sqrt{3}}{120}$.

4MULTIPLE INTEGRALS AND FIELD THEORY Umnov A.E., Umnov E.A.

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Example 02 (1 method) .Calculate $I = \iint_S z \, dx \, dy$, Where S - ellipsoid $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$,
Where $a > 0, b > 0, c > 0$.

$$S: \begin{cases} x(u, v) = a \cos u \cos v, \\ y(u, v) = b \sin u \cos v, \\ z(u, v) = c \sin v, \end{cases}$$

Solution: 1) Parameterize the surface

$$\text{Where } (u, v) \in \Omega = \begin{cases} 0 \leq u < 2\pi \\ -\frac{\pi}{2} \leq v \leq \frac{\pi}{2} \end{cases}.$$

2) Formulate and calculate the integral

$$I = \iint_{\Omega} \det \begin{vmatrix} 0 & 0 & c \sin v \\ -a \sin u \cos v & b \cos u \cos v & 0 \\ -a \cos u \sin v & -b \sin u \sin v & c \cos v \end{vmatrix} \, du \, dv = \iint_{\Omega} H c \sin v \, du \, dv,$$

Where $H = ab \sin v \cos v$.

$$\text{Thus, } I = \iint_{\Omega} abc \sin^2 v \cos v \, du \, dv = \frac{4\pi}{3} abc.$$

Example 02 (2nd method) .Calculate $I = \iint_S z \, dx dy$, Where S - ellipsoid $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$,
 Where $a > 0, b > 0, c > 0$.

Solution: 1) In this case, the surface over which the integral is taken is formed by the graphs

$z(x, y) = \pm c \sqrt{1 - \left(\frac{x^2}{a^2} + \frac{y^2}{b^2} \right)}$, and we represent the integral itself
 of the functions
 in the form

$$I = \pm c \iint_D \sqrt{1 - \left(\frac{x^2}{a^2} + \frac{y^2}{b^2} \right)} \, dx dy$$

Where D – domain of definition of the function $z(x, y)$.

The sign in front of the integral is taken “+” if the normal vector forms an acute angle with the axis *With*, and “-” if this angle is obtuse.

- 2) Let us first take the integral over the upper half of the ellipsoid, moving to generalized polar coordinates:

$$\begin{cases} x = ar \cos \varphi, \\ y = br \sin \varphi. \end{cases}$$

Check for yourself that the module of the Jacobian with such a replacement is equal to abr , and the area D^* there is a rectangle $\{0 \leq r \leq 1, 0 \leq \varphi < 2\pi\}$. Then we get

$$\begin{aligned} I^+ &= abc \iint_{D^*} \sqrt{1-r^2} r dr d\varphi = abc \int_0^{2\pi} d\varphi \int_0^1 \sqrt{1-r^2} r dr = \pi abc \int_0^1 \sqrt{1-r^2} dr^2 = \\ &= \pi abc \left(-\frac{2(1-r^2)^{3/2}}{3} \Big|_0^1 \right) = \frac{2\pi}{3} abc. \end{aligned}$$

For the integral over the lower part of the ellipsoid we have $z(x,y) \leq 0$ and the obtuse angle between the outer normal vector and the positive direction of the axis Oz . This means that the integral over the lower half of the surface I^- will be equal to the integral over the upper I^+ .

$$I = I^+ + I^- = \frac{4\pi}{3} abc.$$

Finally we get

GREEN'S FORMULA

Definition and properties

Let ∂G there is a piecewise smooth contour, which is the boundary of a flat bounded region G .

Then, if the functions $P(x, y)$ And $Q(x, y)$ continuously differentiable in G , then it is fair *Green's formula*

$$\iint_G \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy = \int_{\partial G} P dx + Q dy$$

The direction of bypassing the contour is such that during the bypass the area G remains *left*.

Important: continuous differentiability of functions $P(x, y)$ And $Q(x, y)$ required not only on a piecewise smooth contour ∂G , but also *inside the whole region* G .

Let Γ_{AB} some piecewise smooth line entirely lying in the region G , and A is its beginning, and B is its end. Then the value of the integral $\int_{\Gamma_{AB}} Pdx + Qdy$ does not depend on the shape of the integration trajectory then and only when $\exists u(x, y)$ such that $du = Pdx + Qdy$.

In this case

$$\int_{\Gamma_{AB}} Pdx + Qdy = u(B) - u(A)$$

Necessary condition for the independence of the value of the integral from the path of integration

$$\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y}$$

There is $\frac{\partial Q}{\partial x} = \frac{\partial P}{\partial y}$. And if the area G simply connected, then this condition is sufficient.

Finally, from Green's formula it follows that the area of the region G may be according to the formula

$$S = \iint_G dx dy = \frac{1}{2} \int_{\partial G} x dy - y dx$$

Example 03. Calculate $\int_{\partial G} (1-x^2)y dx + x(1+y^2) dy$, Where $G: \{x^2 + y^2 \leq R^2\}$.

Solution: We have

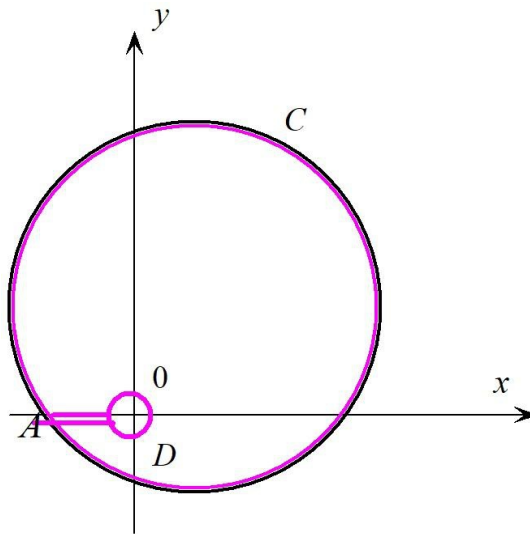
$$\int_{\partial G} (1-x^2)y dx + x(1+y^2) dy = \iint_G (1+y^2 - 1+x^2) dx dy = \iint_G (x^2 + y^2) dx dy =$$

moving to polar coordinates with $J = r dr d\varphi$,

$$= \iint_G r^2 r dr d\varphi = \int_0^{2\pi} d\varphi \int_0^R r^3 dr = \frac{\pi R^4}{2}.$$

Example 04. Calculate $I_C = \int_{\partial G} \frac{xdy - ydx}{x^2 + y^2}$, Where ∂G - a simple contour that does not pass through the origin and goes around the region G , leaving her on the left..

Solution: We have $\frac{\partial Q}{\partial x} = \frac{y^2 - x^2}{x^2 + y^2} = \frac{\partial P}{\partial y}$. Does this mean that $I_C = 0$?
\ Not necessary!



The point is that the original (“black”) integration contour may have *internal singular point* 0.

If the circuit C does not cover this point, then the answer will be $I_C = 0$.

If the special point is inside the “black” contour, then we will construct a “purple” contour (as shown in the figure) by adding a cut $A0$ and a sufficiently small circle enclosing the singular point.

Let the integrals be equal:

I_+ - along the “upper bank” of the section,

I_- - along the “lower bank” of the section,

I_D - in a “small circle” around 0,

I_L - along the "purple" contour.

We have $I_- = -I_+$.

I_D Let's calculate it directly. Let the parameterization of the "small circle" be chosen as

$$\begin{cases} x(t) = a \cos t, \\ y(t) = a \sin t \end{cases} \quad t \in [0, 2\pi)$$

follows:
Where a is a fairly small positive number.

Then, taking into account that when going around the circle D , it remains on the right, we get

$$I_D = \int_D \frac{xdy - ydx}{x^2 + y^2} = \int_{2\pi}^0 \frac{a \cos t \cdot a \cos t - a \sin t \cdot (-a \sin t)}{a^2 (\cos^2 t + \sin^2 t)} dt = - \int_0^{2\pi} dt = -2\pi$$

Finally, $I_L = 0$, since there are no special points inside the "purple" contour.

From the additivity property of the integral it follows that $I_L = I_+ + I_D + I_- + I_C = 0$.
Then the required integral will be equal to

$$I_C = 2\pi$$

SELECTION OF SURFACE SIDE
 (Coordinate system *right rectangular!*)

Parameterization of a smooth surface $S: \vec{r} = \vec{r}(u, v) \quad (u, v) \in \Omega \subseteq E^2$, or in a right-handed rectangular coordinate system: $\begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases}$, determines not only *surface*, but also *her side* direction of the normal vector \vec{n} .

Indeed, let the functions $x(u, v), y(u, v), z(u, v)$ continuously differentiable in Ω and let in Ω point selected (u_0, v_0) .

$$\vec{r}'_u = \begin{pmatrix} \frac{\partial x}{\partial u} \\ \frac{\partial y}{\partial u} \\ \frac{\partial z}{\partial u} \end{pmatrix} \quad \text{And} \quad \vec{r}'_v = \begin{pmatrix} \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial v} \\ \frac{\partial z}{\partial v} \end{pmatrix}$$

Let us introduce the vectors \vec{r}'_u and \vec{r}'_v . If they are non-collinear, then their cross product is non-zero *normal vector* $\vec{n} = [\vec{r}'_u, \vec{r}'_v]$. Such a point (u_0, v_0) usually called *unremarkable*. The normalized normal vector is called *orientation* surface at a point (u_0, v_0) .

At each nonsingular point, the surface can have only two orientations: *positive* $\left[\begin{smallmatrix} \uparrow \\ \vec{n} \\ \downarrow \end{smallmatrix} \right]$ And *negative* $\left[\begin{smallmatrix} \downarrow \\ \vec{n} \\ \uparrow \end{smallmatrix} \right]$. The choice of one of the orientations determines *side* surfaces.

Note, finally, that the orientation can be *continuous* may or may not be a function of a surface point.

An example of the second case is the well-known *Möbius strip*, the parametric form of which can, for example, have the following form:

$$\begin{cases} x(u, v) = (1 + v \cos u) \cos 2u, \\ y(u, v) = (1 + v \cos u) \sin 2u, \\ z(u, v) = v \sin u, \end{cases} \quad \text{with the area} \quad \Omega = \begin{cases} 0 \leq u < \pi, \\ -\frac{1}{2} \leq v \leq \frac{1}{2}. \end{cases}$$

Direction cosines

From the course of linear algebra it is known that in ONB $\{\overset{\boxtimes}{e}_1, \overset{\boxtimes}{e}_2, \overset{\boxtimes}{e}_3\}$ for vector coordinates $\overset{\boxtimes}{r}$ there are equalities $x_i = (\overset{\boxtimes}{r}, \overset{\boxtimes}{e}_i) \quad i = 1, 2, 3$.

From this formula it follows that if $\overset{\boxtimes}{n}$ is a normalized (unit length) vector, then

$$\overset{\boxtimes}{n} = \begin{pmatrix} \cos \alpha \\ \cos \beta \\ \cos \gamma \end{pmatrix}, \text{ Where } \alpha, \beta, \gamma \text{ — angles between the vector } \overset{\boxtimes}{n} \text{ and orts } \{\overset{\boxtimes}{e}_1, \overset{\boxtimes}{e}_2, \overset{\boxtimes}{e}_3\}.$$

Example 05: Cfera S : radius R and with the center at the origin can be parametrically specified as follows:

$$\begin{cases} x = R \cos u \cos v \\ y = R \sin u \cos v \\ z = R \sin v \end{cases} \quad \Omega = \begin{cases} 0 \leq u \leq 2\pi \\ -\frac{\pi}{2} \leq v \leq \frac{\pi}{2} \end{cases}$$

$$\vec{n} = R^2 \begin{vmatrix} \cos u \cos^2 v \\ \sin u \cos^2 v \\ \sin v \cos v \end{vmatrix}$$

At the same time and it is clear that when $v \neq \pm \frac{\pi}{2}$ will $\vec{r} = k\vec{n}$, Where $k = R \cos v > 0$. So this is *positive* orientation and *external* normal

Please note that this parameterization is not *one-to-one* display $\Omega \rightarrow S$.

A surface integral of the second kind, in the case where the orientation of the surface (that is, a continuous vector function $\vec{n}(r)$), given, can be expressed through a surface integral of the first kind.

$$\vec{n} = \begin{vmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \\ x_u & y_u & z_u \\ x_v & y_v & z_v \end{vmatrix} = \vec{e}_1 \cos \alpha + \vec{e}_2 \cos \beta + \vec{e}_3 \cos \gamma$$

Indeed, let $\vec{n} = \vec{e}_1 \cos \alpha + \vec{e}_2 \cos \beta + \vec{e}_3 \cos \gamma$, then the surface integral of the second kind is equal to (this is a definition consistent with the formula in table 5.1!)

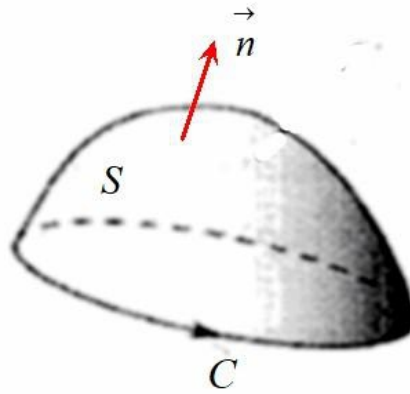
$$\iint_S P dydz + Q dzdx + R dxdy = \iint_S (P \cos \alpha + Q \cos \beta + R \cos \gamma) ds$$

since it is geometrically clear that in an orthonormal coordinate system for a plane figure S , having area ds (and in the limit, for smooth S) the equalities are valid

$$\begin{cases} dxdy = \frac{\partial(x,y)}{\partial(u,v)} dudv = \cos \gamma ds, \\ dydz = \frac{\partial(y,z)}{\partial(u,v)} dudv = \cos \alpha ds, \\ dzdx = \frac{\partial(z,x)}{\partial(u,v)} dudv = \cos \beta ds. \end{cases}$$

Stokes formula

$$\int_C Pdx + Qdy + Rdz = \iint_S \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dxdy + \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} \right) dydz + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} \right) dzdx$$



In the Stokes formula, the direction of traversal of the contour C and the direction of the normal to the surface S must be *agreed upon*.

Agreement means that:

observer moving in the direction of traversing the contour C so that in the direction of the normal S from "feet to head", sees the surface S to your left.

Note that when $dz = 0$ Stokes' formula turns into Green's formula.

Another way to write the Stokes formula

$$\oint_C Pdx + Qdy + Rdz = \iint_S \det \begin{vmatrix} \cos \alpha & \cos \beta & \cos \gamma \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{vmatrix} ds,$$

Where the first row of the determinant matrix contains the direction cosines of the normalized vector \vec{n} , ensuring coordination.

Example 06. Calculate $I_C = \int_C y dx + z dy + x dz$, Where C - circumference

$$\begin{cases} x^2 + y^2 + z^2 = a^2, a > 0 \\ x + y + z = 0 \end{cases}$$
,

oriented counterclockwise when viewed from the end of the axis Ox .

Solution: 1) Integral I_C can be calculated simply by the definition of a curvilinear integral of the second kind. However, in this case it is necessary to find a parametric description of the circle C .

Using the Stokes formula makes it easier to solve the problem. Indeed, since the surface S can be any, then as S let's take part of the plane $x + y + z = 0$, limited by contour C .

$$\vec{n} = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

According to the agreement rule, in our case the normalized vector \vec{n} is the

$$\vec{F} = \begin{pmatrix} y \\ z \\ x \end{pmatrix}$$

same for all points S , and the vector field has the form

2) For derivatives of a vector field

$$\begin{cases} \frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z} = -1 \\ \frac{\partial P}{\partial z} - \frac{\partial R}{\partial x} = -1 \\ \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = -1 \end{cases} .$$

Therefore, finally, using the Stokes formula, we find

$$I_C = \iint_S \left((-1) \frac{1}{\sqrt{3}} + (-1) \frac{1}{\sqrt{3}} + (-1) \frac{1}{\sqrt{3}} \right) ds = -\frac{3}{\sqrt{3}} \iint_S ds = -\pi a^2 \sqrt{3} .$$

Gauss-Ostrogradsky formula

Let S piecewise smooth boundary of a closed region V with *continuously differentiable* vector field, then the formula is valid *Gauss-Ostrogradsky*

$$\iint_S P \, dydz + Q \, dzdx + R \, dxdy = \iiint_V \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} \right) dxdydz,$$

If S – *external* side of the area border V .

Example 02 (3rd method) Calculate $I = \iint_S z \, dx dy$, Where S - ellipsoid $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$,
Where $a > 0, b > 0, c > 0$.

Solution:

Since the surface of the ellipsoid is closed and smooth, we apply the Gauss-Ostrogradsky formula. For a vector field with

$\vec{F}(x, y, z) = \begin{pmatrix} 0 \\ 0 \\ z \end{pmatrix}$ we have $\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = 1$. That's why

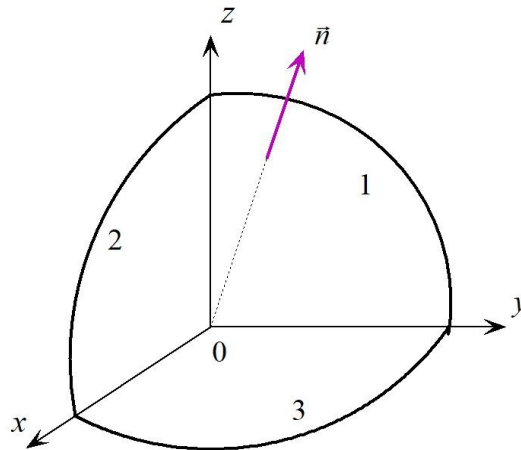
$$I = \iint_S z \, dx dy = \iiint_V dx dy dz$$

The last integral is equal to the volume of the body bounded by the surface S . We know that the volume of a body bounded by an

ellipsoid is equal to $\frac{4\pi}{3} abc$. So, finally,

$$I = \frac{4\pi}{3} abc$$

Example 07. Find $I = \iint_S x^2 y \, dydz + xy^2 \, dzdx + xyz \, dxdy$,
 Where S - part of a sphere $x^2 + y^2 + z^2 = R^2, R > 0$,
 located in the positive octant.



Solution: 1) Since the surface S open, then we will make it closed by adding parts of coordinate planes 1, 2 and 3 to it, as shown in the figure.

2) Note that on coordinate planes 1 and 2 the surface integral *null*, since the vector field is zero, because Here $P = Q = R = 0$.

On a flat boundary 3 the surface integral is also *equal to zero*, in force $\cos \alpha = \cos \beta = 0$
 And $R = 0$.

3) This means that we can apply the Gauss-Ostrogradsky formula for a closed region V . We have

$$\left\{ \begin{array}{l} P(x, y, z) = x^2 y \Rightarrow \frac{\partial P}{\partial x} = 2xy, \\ Q(x, y, z) = xy^2 \Rightarrow \frac{\partial Q}{\partial y} = 2xy, \\ R(x, y, z) = xyz \Rightarrow \frac{\partial R}{\partial z} = xy. \end{array} \right.$$

From where, passing in the triple integral to spherical coordinates

$$\left\{ \begin{array}{l} x = r \cos \varphi \cos \psi, \\ y = r \sin \varphi \cos \psi, \\ z = r \sin \psi, \end{array} \right.$$

get

$$\begin{aligned} I &= \iiint_V 5xy \, dx dy dz = 5 \int_0^{\frac{\pi}{2}} d\varphi \int_0^{\frac{\pi}{2}} d\psi \int_0^R (r \cos \varphi \cos \psi) \cdot (r \sin \varphi \cos \psi) r^2 \cos \psi \, dr = \\ &= R^5 \int_0^{\frac{\pi}{2}} \cos \varphi \sin \varphi \, d\varphi \int_0^{\frac{\pi}{2}} \cos^3 \psi \, d\psi = \frac{1}{3} R^5. \end{aligned}$$